# POINTERS

### **OVERVIEW**



- Pointers are special variables that can contain the memory address of another variable
- We can use pointers to access and modify variables
  - Special C++ syntax to get address and follow pointer
- We can also create dynamic data structures that grow and shrink with the needs of an application
  - Special C++ commands to allocate and release memory



 Memory on a computer can be viewed as a very long array divided into seven parts

Operating system code	
Operating system data	
Program code	
Program data	
Run time stack	
Empty space	
Run time heap	

The operating system keeps track of all of the programs that are running on the computer



 Memory on a computer can be viewed as a very long array divided into seven parts





 Memory on a computer can be viewed as a very long array divided into seven parts



### **OVERVIEW**

#### Lesson objectives:

- Learn the basic syntax for pointer variables
- Learn how to use pointers to access/modify variables
- Learn about the run time stack and run time heap
- Learn how to allocate and release dynamic memory
- Study example program with dynamic memory
- Study example class with dynamic memory

# POINTERS

# PART 1 POINTER BASICS

### **POINTER VARIABLES**

- A pointer variable allows us to store the memory address of another variable in the program
  - We can them use this pointer variable to access and modify the original variable
  - We can also use pointer variables to create dynamic data structures that grow/shrink with needs of program
- Pointers can only "point to" variables of one data type
  - An integer pointer can store address of an integer variable
  - A float pointer can store address of a float variable
  - A char pointer can store address of a char variable

### **POINTER VARIABLES**

- We declare pointer variables using a \* operator between he data\_type and the variable\_name
  - int \* ptr1 will declare an integer pointer
  - float \* ptr2 will declare a float pointer
  - char \* ptr3 will declare a char pointer
- It does not matter where the \* is placed
  - int\* ptr1 it can go next to the data\_type
  - float \*ptr2 it can go next to the variable\_name
  - char \* ptr3 it can go half way in between

#### We need some way to obtain the address of variables

- The address operator & gives address of following variable
- We can store this address in a pointer variable

int a = 42; int b = 17;

int \*aptr = &a; < aptr now contains address of a int \*bptr = &b; < bptr now contains address of b

- Every time we run a program, the operating system will give our program a different portion of memory to run in
  - This means that the memory addresses we get with the address operator could be different every time!

int a = 42;int b = 17;

int \*aptr = &a; 
int \*bptr = &b;

First time we run program aptr = 1000 Next time we run program aptr = 1234 We can not predict this value

- Variables are assigned to consecutive memory locations
  - The differences between variable memory addresses will be the same every time we run the program

int a = 42; int b = 17;

• We can print addresses just like any other variable

cout << aptr << endl; cout << &b << endl;

Memory addresses are normally printed in hexadecimal

- Starts with "0x" to indicate value is in hexadecimal
- Followed by N hexadecimal digits (0123456789abcdef)
- Linux uses 12 hexadecimal digits (48-bits) for addresses
- Eg: 0x7fff541aec3c 0x7fff541aec38

# INDIRECTION OPERATOR

#### We need some way to "follow pointers" to variables

- The indirection operator \* is used to do this
- When we put \* in front of a pointer variable we can access or modify the variable at that memory location

float n = 3.14; float \*ptr = &n;

\*ptr = 1.23; \*ptr is another way to access the variable n, so now n equals 1.23
Cout << n << endl; // will print 1.23

# INDIRECTION OPERATOR

#### It is possible to have multiple pointers to one variable

 We must assign one pointer value (address) to another pointer variable of the same type

```
float n = 3.14;
float *ptr = &n;
float *ptr2 = ptr;
```



We now have three ways to change the value of variable n

# ARRAYS AND POINTERS

#### Arrays and pointers are actually very similar in C++

- When we declare "int data[10]" the variable "data" stores the <u>address</u> of the first array element
- This means that the indirection operator \* can be used with the array name to access variables in an array



## ARRAYS AND POINTERS

- We can also use array subscripts [] and pointer variables to access and modify variables
  - We have to be very careful with array bounds



# ARRAYS AND POINTERS

- It is possible to do some very sneaky programming using arrays and pointers
  - When we add one to a pointer variable, we point to adjacent variable of the same data type
  - This pointer arithmetic gives us another way to access variables in an array (very ugly and not recommended)



- In this section, we went over the syntax for declaring and using pointers in C++
  - We declare pointer variables by adding \* between the data\_type and variable\_name
  - The address operator & is used to get the current memory address of a variable
  - The indirection operator \* is used to "follow" a pointer and access the variable at that address
  - Arrays and pointers are similar in several ways and can be accessed using similar notation

# POINTERS

# PART 2 DYNAMIC DATA STRUCTURES

- The run time stack is used to give a program space for function parameters and local variables
  - The stack "grows" in size for every function call
  - Growth size depends on the number and types of the parameters and local variables
  - The stack "shrinks" in size when the function finishes
- If there is infinite recursion in a program, the stack will use up all available empty space and the program will die with a "stack overflow" error

Consider the following program

```
int process(int number)
{
    int result = (number + 5) / 2;
    return result;
}
```

The process function has one
integer parameter and one integer variable and needs 8 bytes

```
int main()
{
    int value = process(17);
    cout << value;
    return 0;
}</pre>
```

#### Consider the following program

```
int process(int number)
{
    int result = (number + 5) / 2;
    return result;
```

}

{

int main()

```
int value = process(17);
cout << value;
return 0;
```

The main function has one integer variable and needs 4 bytes

 When the program starts, the stack grows to contain space for variables in the "main" function



 When the function "process" is called, the stack grows to contain space for variables in this function



 When the function "process" returns its result, we no longer need the space for these local variables, so the stack shrinks in size

value:	11
--------	----

# **RUN TIME HEAP**

- The run time heap is used to give a program space for dynamic variables
  - The user can "allocate" space on the heap for a variable
  - The size of the variable can be decided at run time to exactly meet the needs of the application
  - The user must "release" space to the heap when finished using the dynamic variable
- If space is not returned properly, a program can have a "memory leak" and may run out of space and die

# DYNAMIC MEMORY ALLOCATION

#### The "new" command allocates memory

- We allocate space for one variable using "new data\_type"
- This will return the <u>address</u> of the allocated memory
- We use the indirection operator \* to access this variable

```
float *ptr;
ptr = new float;
*ptr = 42;
```

# DYNAMIC MEMORY ALLOCATION

#### The "new" command can also allocate space for arrays

- We have to specify the data\_type
- We also have to specify how much space to allocate
- The syntax is similar to how we declare arrays
- We can access this dynamic memory using [] notation

# RELEASING DYNAMIC MEMORY

- The "delete" command releases memory
  - When we are finished using a dynamic variable we must release its memory using "delete pointer\_name"
  - The operating system will then add this memory to the "empty space" between the stack and the heap

```
float *ptr;

ptr = new float;

*ptr = 42;

...

delete ptr;

ptr = NULL; ←
```

delete ptr;<br/>ptr = NULL; ←You should never attempt to use \*ptr<br/>after you have called delete because<br/>you no longer "own" this memory

# RELEASING DYNAMIC MEMORY

#### The "delete []" command also releases memory

- When we are finished using a dynamic array we must release its memory using "delete [] pointer\_name"
- The operating system will then add this memory to the "empty space" between the stack and the heap

```
int * ptr;
ptr = new int[10];
```

You should never attempt to use ptr[i] after you have called delete because you no longer "own" this memory

. . .

- Assume we are given an ascii file containing an unknown number of integer values and we want to sort this data
  - We do not want to "guess" the size of data array
  - Guess too high  $\rightarrow$  waste memory space
  - Guess too low  $\rightarrow$  program fails to work properly

#### • Our algorithm:

- Read input file to count how many values are in file
- Allocate a dynamic array large enough for this data
- Read data from input file into the dynamic array
- Perform sorting algorithm on data in array
- Print sorted data and release memory

#### // Read input file to count values

ifstream din;

```
din.open("numbers.txt");
```

```
int count = 0;
```

```
int number = 0;
```

```
while (din >> number) ←
```

count++;

din.close();

This read operation returns "true" if data is read correctly and "false" when we reach the end of file

#### // Allocate dynamic array

int \* data;

data = new int[count];

The count variable was initialized above so we can allocate exactly the right size array to process this data

#### // Read data into dynamic array

din.open("numbers.txt");

```
for (int i=0; i<count; i++)
```

din >> data[i];

din.close();

We can read data in a for loop without checking for end of file because we know exactly how many values there are in the input file

#### // Sort data using bubble sort

```
for (int i=0; i<count; i++)
for (int j=1; j<count; j++)
if (data[j-1] > data[j])
{
    int temp = data[j-1];
    data[j-1] = data[j];
    data[j] = temp;
}
```

#### // Print sorted data and release memory

```
for (int i=0; i<count; i++)
```

```
cout << data[i] << " ";
```

cout << endl;

We are finished with the data delete [] data; 
array so we can release this memory to the "free space"

### **SUMMARY**

#### The run time stack is used for variables in functions

- Grows and shrinks as we call functions and return
- The run time heap is used for dynamic variables
  - Grows and shrinks as we allocate and release memory
- The "new" command allocates space on heap
  - int \*ptr = new int[10];
- The "delete" command releases memory
  - delete [] ptr;

# POINTERS

# PART 3 POINTERS IN CLASSES

# POINTERS IN CLASSES

- Pointers and dynamic memory allocation are often used in classes to create dynamic abstract data types (ADTs)
  - Memory is allocated in constructor methods
  - Memory is released in destructor methods
  - This way the ADT can grow/shrink as needed
  - This approach will help us avoid memory leaks

# POINTERS IN CLASSES

#### Dynamic ADTs fall into two categories

- Array based
  - Where a dynamic array grows/shrinks to store data
  - The C++ "vector" class uses this approach
- Node based
  - Where data is stored in a collection of "nodes"
  - Pointers are used to link these nodes together
  - "linked lists" and "binary trees" use this approach
  - These ADTs will be studied in detail in PF2

### **MYARRAY CLASS**

#### The "MyArray" class demonstrates use of dynamic array

- The "Data" variable contains a pointer to dynamic memory
- The "Size" variable contains size of dynamic memory

```
class MyArray
{
private:
int * Data;
int Size;
```

• • •

### **MYARRAY CLASS**

Access to this memory will be provided by class methods

public:

. . .

```
MyArray(const int size = 10);
MyArray(const MyArray & array);
~MyArray();
```

```
int Get(const int index);
void Set(const int index, const int value);
void Resize(const int size);
};
```

# CONSTRUCTOR

 If we want to create an ADT using a dynamic array we must allocate memory in the constructor method

```
MyArray::MyArray(const int size)
{
    Size = size;
    Data = new int[Size];
    for (int i=0; i<Size; i++)
    Data[i] = 0;
}
```

# **COPY CONSTRUCTOR**

 The copy constructor method for a dynamic array ADT must allocate memory and copy array data

```
MyArray::MyArray(const MyArray & array)
{
    Size = array.Size;
    Data = new int[Size];
    for (int i=0; i<Size; i++)
    Data[i] = array.Data[i];
}
```

### DESTRUCTOR

 The destructor method is automatically called when an object is no longer "in scope" and no longer needed

```
MyArray::~MyArray()
{
    delete []Data;
    Size = 0;
    Data = NULL;
}
```

Setting the pointer to NULL makes it clear to users of this class that the array can no longer be accessed

### **GET METHOD**

To access data in the the array, we use Get method

```
int MyArray::Get(const int index)
{
    if ((index >= 0) && (index < Size))
        return Data[index];
    else
        return -1;
    }
    We perform error
    checking on index before
    we access the Data</pre>
```

### **GET METHOD**

To access data in the the array, we use Get method

```
bool MyArray::Get(const int index, int & value)
{
    if ((index >= 0) && (index < Size))
    {       value = Data[index];
        return true; }
    else
        return false;
    }
</pre>
We perform error
checking on index before
we access the Data
```

### **GET METHOD**

To access data in the the array, we use Get method

```
bool MyArray::Get(const int index, int & value)
{
    if ((index < 0) || (index >= Size))
        return false;
    value = Data[index];
    return true;
    We perform error
    checking on index before
    we access the Data
```

### **SET METHOD**

To store data in the the array, we use Set method

```
void MyArray::Set(const int index, const int value)
{
    if ((index >= 0) && (index < Size))
        Data[index] = value;
}
We perform error
    checking on index before</pre>
```

we access the Data

### **RESIZE METHOD**

 To resize the array, we must allocate a new array of desired size and copy all of the old data into new array

## **RESIZE METHOD**

```
// copy old data into new array
for (int i=0; i<size && i<Size; i++)
    Data[i] = OldData[i];
                                     This will result in data loss if the
// release old memory
                                     new size is less than old Size
Size = size;
delete [] OldData;
}
                               We return memory for the original
                               Data array back to the heap
```

# **USING MYARRAY**

```
#include "MyArray.h"
int main()
{
    // Create array
    int size = 0;
    cout << "Enter array size:";
    cin >> size;
    MyArray data(size);
```

```
// Set array values
for (int index = 0; index < size; index++)
    data.Set(index, random() % 17);</pre>
```

# **USING MYARRAY**

```
// Print array values
for (int index = 0; index < size; index++)
    cout << data.Get(index) << " ";
cout << endl;</pre>
```

```
// Resize the array
cout << "Enter new array size: ";
cin >> size;
data.Resize(size);
```

# **USING MYARRAY**

```
// Update array values
for (int index = 0; index < size; index++)
    data.Set(index, data.Get(index) + 42);</pre>
```

```
// Print array values
for (int index = 0; index < size; index++)
    cout << data.Get(index) << " ";
    cout << endl;
    return 0;
} The destructor function is
    called automatically here</pre>
```

. . .



- The MyArray class could be extended to include a wide variety of operations
  - Min / Max / Mean / Standard Deviation methods
  - Searching / Sorting / Median methods
  - Input / Output methods
- Similar dynamic arrays have been created for signal processing and image processing applications
  - Grow to fit the size of input audio file or image
  - Contain hundreds of specialized operations



- Pointers and dynamic memory allocation are often used in classes to create dynamic abstract data types (ADTs)
  - Memory is allocated in constructor methods
  - Memory is released in destructor methods
  - This way the ADT can grow/shrink as needed
  - This approach will help us avoid memory leaks
- In this section, we described how an "array based" dynamic ADT can be implemented in C++
- In future classes you will learn about "node based" dynamic ADTs (linked lists, binary trees, etc)

